

The assertion proved below on the run time required by certain programs is a generalized version of the halting problem, and shares with it simplicity of proof and intuitiveness of the result.

Suppose $T(P)$ is a timing program which takes an arbitrary program P with no free variables as its argument, and that for all such P , $T(P) = \text{TRUE}$ if P terminates execution in time less than t when run, and $T(P) = \text{FALSE}$ if P runs for at least time t . Suppose further that all programs P as well as the timing program T ran on the same computer C , and that identical programs will always have equal run times on C .

Then for some argument program Q , $T(Q)$ must run at least for time $t - \epsilon$ where ϵ is some ("small") positive constant dependent on C but independent of t .

Liberally interpreted, this result says that the best one can do in general to estimate the run time of programs is to execute them. The ϵ in the assertion above is vexing, since one intuitively expects the stronger statement that $T(Q)$ must run at least for time t , or even $t + \epsilon$. However, it does not seem that the proof below can be sharpened to yield a stronger result. The proof is as follows.

Consider a program Q which, in a free notation, is expressed by Q : recursive procedure; if $T(Q)$ then run for time t ; return; end. Notice that t is some fixed number, hence Q has no free variables and qualifies as an argument for T . Notice also that $T(Q)$ cannot have the value TRUE because if it had, Q would run for at least time t , contradicting our assumption on the behavior of T . Hence $T(Q)$ must be FALSE , and hence the run time $r(Q)$ of Q must be at least t . According to the definition of Q , its run time $r(Q)$ consists of two parts: 1) the time $r(T(Q))$ required to compute the value of $T(Q)$, plus 2) the time to enter the procedure Q , to branch on FALSE , and to return. The time required for the latter control operation clearly does not depend on T (and hence not on the time limit t), and we denote it by ϵ .

Hence we have

$$r(Q) = r(T(Q)) + \epsilon \geq t,$$

and

$$r(T(Q)) \geq t - \epsilon,$$

which was to be demonstrated.

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REFERENCE

- [1] C. Strachey, "An impossible program," (Letter to the Editor), *Computer J.*, vol. 7, no. 4, p. 313, January 1965.

Comment on "The Determination of the Maximum Compatibility Classes"

A recent correspondence by Choudhury, Basu, and DeSarkar [1] describes an algebraic method for determining the maximal compatibles of an incompletely specified sequential machine. This method appears in an earlier paper by Marcus [3], who attributes the basic idea to Weissman [4]. One of this writer's students, Major T. G. Purnhagen, of the U. S. Air Force, points out that the method was also discovered by Lipovski [2].

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[2] G. J. Lipovski, "An improved method of finding all largest combinable classes," Coordinated Science Laboratory, University of Illinois, Urbana, Rept. R-362, August 1967.
[3] M. P. Marcus, "Derivation of maximal compatibles using Boolean algebra," *IBM J. Res. and Develop.*, vol. 8, pp. 537-538, November 1964.
[4] J. Weissman, "Boolean algebra, map coloring, and interconnections," *Am. Math. Monthly*, vol. 69, pp. 608-613, September 1962.

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Authors' Reply

Having gone through the paper by Marcus [1], we agree that our method [2] of finding the maximum compatibles is essentially similar to his approach. However, our method was developed independently. The different issues of the IBM journals are not available to us.

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[2] A. K. Choudhury, A. K. Basu, and S. C. DeSarkar, "On the determination of the maximum compatibility classes," *IEEE Trans. Computers* (Correspondence), vol. C-18, p. 665, July 1969.

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